

# Project 8: Maximal Equicontinuous Factor

Matti Bleckmann, Jannik Daun, Pablo Lummerzheim

Coordinator: Lino Haupt

ISEM28, 2025

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## Definition (Topological Dynamical System (TDS))

Let  $(X, d)$  be a **compact** metric space and  $T$  a topological group and let there be a continuous map  $T \times X \rightarrow X$   $((t, x) \mapsto tx)$  such that for all  $s, t \in T$  and  $x \in X$

- $ex = x$
- $(st)x = s(tx)$ .

Then we call  $(X, T)$  a **topological dynamical system** (TDS).

## Remark

*Note that for each  $t \in T$  the map  $x \mapsto tx$  is a homeomorphism.*

## Remark

*Let  $\alpha : X \rightarrow X$  be a homeomorphism. Then this gives rise to a  $\mathbb{Z}$  action with  $n\alpha := \alpha^n(x)$  for  $n \in \mathbb{Z}$ . In this case we write  $(X, \alpha)$  for this dynamical system.*

## Definition (Factors and Isomorphisms)

A TDS  $(Y, T)$  is a **factor** of  $(X, T)$  if there exists a **factor map**, i.e. a surjective and continuous map

$$\pi : X \rightarrow Y$$

such that  $\pi(tx) = t\pi(x)$  for all  $t \in T$ ,  $x \in X$ .

A factor map is a **conjugacy** (of TDS) if it is a homeomorphism.

Two TDS are conjugated if there exists an conjugacy between them.

## Definition (ICER and Quotient)

An **invariant closed equivalence relation** (ICER)  $R \subseteq X \times X$  is a equivalence relation, such that  $R$  is closed and  $tR = R$  for all  $t \in T$ .

Then the quotient  $X/R$  becomes a TDS with  $t[x] := [tx]$  for all  $t \in T$  and  $x \in X$ .

## Proposition

Let  $R \subseteq X \times X$  be an ICER. Then we can define a factor by

$$\pi_R : X \rightarrow X/R \quad \pi_R(x) := [x] \quad \forall x \in X.$$

Let  $\pi : X \rightarrow Y$  be a factor map. Then we can define an ICER by

$$R_\pi := \{(x, y) \in X \times X \mid \pi(x) = \pi(y)\}.$$

In this case we have  $(Y, T) \cong (X/R_\pi, T)$ .

## Definition (Conjugated and Equivalent factors)

Let  $(Y, T)$  and  $(Z, T)$  be two factors of  $(X, T)$  with factor maps  $\pi$  and  $\rho$ .

The factors are **equivalent** if  $R_\pi = R_\rho$ .

The factors are **conjugated** if  $(Y, T) \cong (Z, T)$ .

### Definition (Equicontinuous TDS)

The TDS  $(X, T)$  is **equicontinuous** if for  $\varepsilon > 0$  there is some  $\delta > 0$  such that

$$d(x, y) < \delta \Rightarrow d(tx, ty) < \varepsilon$$

for all  $x, y \in X$  and  $t \in T$ .

### Remark

*Intuitively equicontinuity means that two points that are close, were always and will always be close.*

### Definition (Equicontinuous TDS)

The TDS  $(X, T)$  is **equicontinuous** if for  $\varepsilon > 0$  there is some  $\delta > 0$  such that

$$d(x, y) < \delta \Rightarrow d(tx, ty) < \varepsilon$$

for all  $x, y \in X$  and  $t \in T$ .

### Proposition

*Let  $d, \tilde{d}$  be two metrics on  $X$ , that induce the same topology. Then  $(X, T)$  is equicontinuous with respect to  $d$  if and only if it is equicontinuous with respect to  $\tilde{d}$ .*

### Proposition

*For an equicontinuous action we can always choose a metric, inducing the same topology, that is invariant under the action.*

### Definition (Equicontinuous TDS)

The TDS  $(X, T)$  is **equicontinuous** if for  $\varepsilon > 0$  there is some  $\delta > 0$  such that

$$d(x, y) < \delta \Rightarrow d(tx, ty) < \varepsilon$$

for all  $x, y \in X$  and  $t \in T$ .

### Proposition

*Equicontinuity is preserved under conjugacies, (countable) products and subsystems.*



## Example: Circle Rotations $\mathbb{Z}$ -action

We look at the circle  $\mathbb{T} := \mathbb{R}/\mathbb{Z}$  (identify  $[x] = x + \mathbb{Z}$  for  $x \in \mathbb{R}$  with  $e^{2\pi i x}$  in  $\mathbb{C}$ ).

The metric on  $\mathbb{T}$  is given by

$$d_{\mathbb{T}}([x], [y]) := \min_{n \in \mathbb{Z}} |x - y + n|.$$

Fix  $a \in \mathbb{R}$  and define

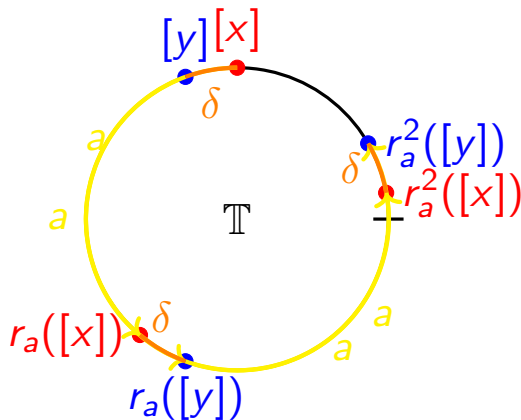
$$r_a([x]) := [x + a].$$

The TDS  $(\mathbb{T}, r_a)$  is minimal iff  $a \notin \mathbb{Q}$ .

We have for  $[x], [y] \in \mathbb{S}$  and  $n \in \mathbb{Z}$  that

$$d_{\mathbb{T}}(r_a^n([x]), r_a^n([y])) = d_{\mathbb{T}}([x], [y]),$$

i.e.  $r_a$  is isometric. Equicontinuity is an immediate consequence.



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Let  $(X, T)$  be a TDS.

### Definition (maximal equicontinuous factor (MEF))

A factor  $\pi : (X, T) \rightarrow (X_{\text{MEF}}, T)$  is a **MEF** of  $(X, T)$  if and only if

- $(X_{\text{MEF}}, T)$  is equicontinuous,
- $\pi$  is maximal:  $\forall \varphi : (X, T) \rightarrow (Y, T)$  factor s.t.  $(Y, T)$  equicontinuous:  $R_\pi \subseteq R_\varphi$ .

### Theorem (existence and uniqueness of the MEF)

$(X, T)$  has a MEF that is unique up to equivalence.

### Example (MEF of equicontinuous TDS is original TDS)

$(X, T)$  equicontinuous, then  $I : (X, T) \rightarrow (X, T)$  is the MEF of  $(X, T)$ .

## Proposition (universal property of the MEF)

Let  $\pi : (X, T) \rightarrow (X_{MEF}, T)$  be the MEF.

$\forall \varphi : (X, T) \rightarrow (Y, T)$  factor with  $(Y, T)$  equicontinuous :

$\exists!$  factor  $\tilde{\varphi} : (X_{MEF}, T) \rightarrow (Y, T) : \varphi = \tilde{\varphi} \circ \pi$

$$\begin{array}{ccc}
 (X, T) & \xrightarrow{\varphi} & (Y, T) \text{ equic.} \\
 \pi \downarrow & \nearrow \exists! \tilde{\varphi} & \\
 (X_{MEF}, T) & & 
 \end{array}$$

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$(X, T)$  TDS with  $T$  abelian,  $T^\#$  ( $T^*$ ) the set of all (continuous) characters of  $T$ .

### Definition (Koopman representation)

$$U : T \longrightarrow \mathcal{L}(C(X))$$

$$(U(t)f)(x) := f(tx)$$

### Remark

$T$ -action continuous on  $T \times X \Rightarrow U$  strongly continuous  $T$ -representation  
(for proof see [EFHN15], Theorem 4.17)

### Definition (eigenvalue, eigenfunction)

$$0 \neq f \in C(X) \text{ eigenfunction of } U \text{ to eigenvalue } \chi \in T^*$$

$$:\Leftrightarrow f \in \ker(U - \chi) := \bigcap_{t \in T} \ker(U(t) - \chi(t)I)$$

## Definition (discrete spectrum)

$$(X, T) \text{ has (TDS) **discrete spectrum** } :\Leftrightarrow C(X) = \overline{\text{lin}} \bigcup_{\chi \in T^*} \ker(U - \chi)$$

## Theorem (equicontinuity $\Leftrightarrow$ discrete spectrum)

$$(X, T) \text{ is equicontinuous } \Leftrightarrow (X, T) \text{ has discrete spectrum}$$

(for proof see [HK23], Theorem 2.11)

## Theorem (MEF eigenfunction characterisation)

Let  $\pi : (X, T) \rightarrow (X_{\text{MEF}}, T)$  be the MEF. Then  $\forall x_1, x_2 \in X$ :

$$\pi(x_1) = \pi(x_2) \Leftrightarrow \forall f \in \bigcup_{\chi \in T^*} \ker(U - \chi) : f(x_1) = f(x_2)$$



## Intermezzo: Duality of categories!

- $\mathbf{C} :=$  category of commutative unital  $C^*$ -algebras,
- $\mathbf{D} :=$  category of compact Hausdorff spaces,
- contravariant Gelfand functor  $G : \mathbf{C} \rightarrow \mathbf{D}$ ,  
 $G(\mathcal{A}) := \{\varphi : \mathcal{A} \rightarrow \mathbb{C} \mid \varphi \text{ morphism}\}$  with the weak-\* topology,  
 $G(\Psi : \mathcal{A} \rightarrow \mathcal{B}) : G(\mathcal{B}) \rightarrow G(\mathcal{A}), \varphi \mapsto \varphi \circ \Psi,$
- contravariant continuous function functor  $C : \mathbf{D} \rightarrow \mathbf{C}, X \mapsto C(X),$   
 $C(f : X \rightarrow Y) : C(Y) \rightarrow C(X), g \mapsto g \circ f,$
- evaluation map  $\text{eval} : I \Rightarrow GC, \text{eval}(x)f := f(x)$  is natural isomorphism,
- Gelfand transform  $\hat{\phantom{x}} : I \Rightarrow CG, \hat{a}(\varphi) := \varphi(a)$  is natural isomorphism.

## MEF via $C^*$ -algebras

- $\mathcal{A} := \overline{\text{lin}} \bigcup_{\chi \in T^*} \ker(U - \chi) \subseteq C(X)$ ,
- $\mathcal{A}$  is smallest unital  $C^*$ -subalgebra containing all eigenfunctions of  $U$ ,
- $\mathcal{A}$   $U$ -invariant  $\rightarrow T$ -action on  $G(\mathcal{A})$ :  
$$t \cdot \varphi := G(U(t))\varphi,$$
- $\iota : \mathcal{A} \rightarrow C(X)$  natural injection,
- $G(\iota) : G(C(X)) \rightarrow G(\mathcal{A})$ ,
- **MEF of  $(X, T)$  is**  
$$\pi : (X, T) \rightarrow (G(\mathcal{A}), T),$$
  
$$\pi := G(\iota) \circ \text{eval},$$

- $\hat{\cdot} : I \Rightarrow CG$  natural:

$$\begin{array}{ccc} \mathcal{A} & \xrightarrow{\hat{\cdot}} & C(G(\mathcal{A})) \\ \downarrow \iota & \circlearrowleft & \downarrow C(G(\iota)) \\ C(X) & \xrightarrow{\hat{\cdot}} & C(G(C(X))) \end{array}$$

- $G(\iota)$  surjective  $\Leftrightarrow C(G(\iota))$  injective  
 $\Leftrightarrow \iota$  injective,
- let  $x_1, x_2 \in X$ :  
$$\pi(x_1) = \pi(x_2) \Leftrightarrow \forall f \in \mathcal{A} : f(x_1) = f(x_2)$$
  
$$\Leftrightarrow \forall f \in \bigcup_{\chi \in T^*} \ker(U - \chi) : f(x_1) = f(x_2).$$

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# MEF vs. Kronecker subsystem

$T$  still abelian

$(X, T)$  TDS

- Koopman rep.  $U : T \rightarrow \mathcal{L}(C(X))$ ,
- $(X, T)$  has discrete spectrum  
 $\Leftrightarrow \overline{\text{lin}} \bigcup_{\chi \in T^*} \ker(U - \chi) = C(X)$ ,
- MEF: associated to the  $U$ -invariant  $C^*$ -subalgebra

$$\overline{\text{lin}} \bigcup_{\chi \in T^*} \ker(U - \chi) \subseteq C(X).$$

$(Y, T)$  measure preserving system (MPS)

- Koopman rep.  $V : T \rightarrow \mathcal{L}(L^2(Y))$ ,
- $(Y, T)$  has discrete spectrum  
 $\Leftrightarrow \overline{\text{lin}} \bigcup_{\chi \in T^\#} \ker(V - \chi) = L^2(Y)$ ,
- Kronecker subsystem: associated to the  $V$ -invariant Markov sublattice

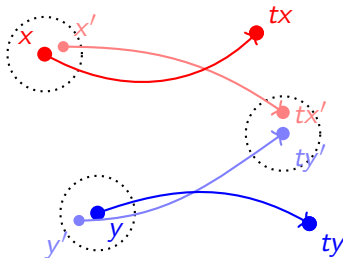
$$\overline{\text{lin}} \bigcup_{\chi \in T^\#} \ker(V - \chi) \subseteq L^2(Y).$$

**MEF is the TDS analogue of the Kronecker subsystem!**

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## Definition (regionally proximal relation)

Let  $(X, T)$  be a TDS. Two points  $x, y \in X$  are called *regionally proximal* if for each  $\varepsilon > 0$  there exist  $x' \in B_\varepsilon(x)$ ,  $y' \in B_\varepsilon(y)$  and  $t \in T$  such that  $d(tx', ty') < \varepsilon$ . We denote the set of regionally proximal pairs by  $Q_2(X) \subseteq X \times X$ .



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Equivalently: There is  $(x_n), (y_n)$  in  $X$  and  $(t_n)$  in  $T$ , s.t.

$$x_n \rightarrow x, y_n \rightarrow y \text{ and } d(t_n x_n, t_n y_n) \rightarrow 0.$$

and

$$Q_2(X) = \bigcap_{U \in \mathcal{U}(\Delta(X))} \overline{TU}$$

with  $\Delta(X) = \{(x, x) \mid x \in X\}$  the diagonal in  $X \times X$ .

## Theorem

*The regionally proximal relation is closed, invariant, symmetric and reflexive.*

- ① symmetric and reflexive by definition
- ② closed, since intersection of closed sets
- ③ invariant:  $(x, y) \in Q_2(X)$ , i.e.  $d(t_n x_n, t_n y_n) \rightarrow 0$  then  
 $d(t_n t_0^{-1} t_0 x_n, t_n t_0^{-1} t_0 y_n) \rightarrow 0$ .

Not transitive in general! See Example.



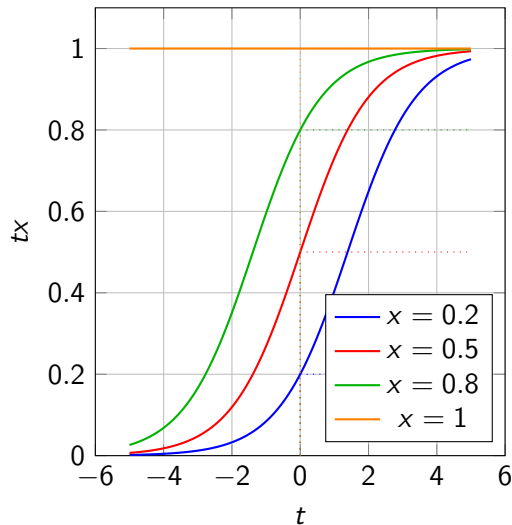
Let  $X = [0, 2]$  and  $T = \mathbb{R}$ . Then the following map is an  $\mathbb{R}$ -action on  $[0, 2]$  and defines a TDS.

$$\mathbb{R} \times [0, 2] \rightarrow [0, 2]$$

$$(t, x) \mapsto tx := \begin{cases} 0 & x = 0 \\ \frac{1}{1 + (\frac{1}{x} - 1)e^{-t}} & x \in (0, 1] \\ \frac{1}{1 + (\frac{1}{x-1} - 1)e^{-t}} + 1 & x \in (1, 2] \end{cases}$$

Every point greater 0 and smaller 1 tends to 1 and every point greater 1 tends to 2 with  $t \rightarrow \infty$ .

We also observe that  $\{0\}$ ,  $\{1\}$  and  $\{2\}$  are closed invariant.

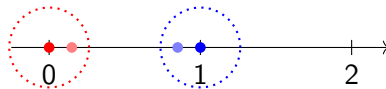


Consider the system from the previous slide.

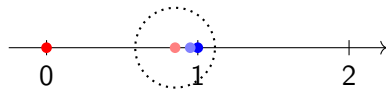
The pairs  $(0, 1)$  and  $(1, 2)$  are regionally proximal.

But  $(0, 2)$  is not a regionally proximal pair.

For 0 and 1 we have:



With  $t$  large enough:



## Proposition

*Let  $\varphi : (X, T) \rightarrow (Y, T)$  a factor. Then  $(\varphi \times \varphi)(Q_2(X)) \subseteq Q_2(Y)$ .*

## Theorem

*Let  $(X, T)$  a TDS and  $\varphi : (X, T) \rightarrow (Y, T)$  an equicontinuous factor. Let  $R_\varphi$  the ICER generated by  $\varphi$ . Then  $Q_2(X) \subseteq R_\varphi$ .*

Proof by contradiction using the invariant metric.

## Corollary

*Let  $(X, T)$  be an equicontinuous TDS. Then  $Q_2(X) = \Delta(X)$ .*

The identity map with  $\Delta(X)$  as ICER is an equicontinuous factor.

Since the MEF is an equicontinuous factor, we have

### Corollary

*Let  $(X, T)$  be a TDS and  $R_{MEF}$  the ICER generated by the MEF. Then  $Q_2(X) \subseteq R_{MEF}$ .*

Do we also have  $R \subseteq Q_2(X)$ ?

But first:

### Definition (topologically weakly mixing)

Let  $(X, T)$  be a TDS. Then  $(X, T)$  is called *weakly mixing* if every non-empty,  $T$ -invariant and open  $U \subseteq X \times X$  is dense in  $X \times X$ .

### Proposition (weakly mixing systems have trivial $Q_2$ )

Let  $(X, T)$  be a weakly mixing TDS. Then  $Q_2(X) = X \times X$ .

Using the theorem of Baire and the characterization of the regionally proximal equation using intersections.

### Corollary (MEF of weakly mixing system)

The MEF of a weakly mixing system is trivial.

Since  $Q_2(X) = X \times X \subseteq R_{\text{MEF}}$ .

$(X, T)$  equicontinuous

- ① MEF is the identity map, biggest possible factor
- ②  $Q_2(X) = \Delta(X)$ , smallest possible reflexive relation

$(X, T)$  weakly mixing

- ① MEF is one-point system, smallest possible factor
- ②  $Q_2(X) = X \times X$ , biggest possible relation

We have  $Q_2(X) = R_{MEF}$  with some assumptions.

### Theorem

*Let  $(X, T)$  be a minimal TDS with an invariant Borel probability measure and  $R_{MEF}$  be the ICER associated with the MEF of  $X$ . Then  $Q_2(X) = R_{MEF}$ .*

Note that minimality is important for  $Q_2(X)$  being an equivalence relation (see Example). For a proof see [Aus88, p.130, Thm. 8.].

The condition of having an invariant Borel probability measure is always satisfied for abelian groups.

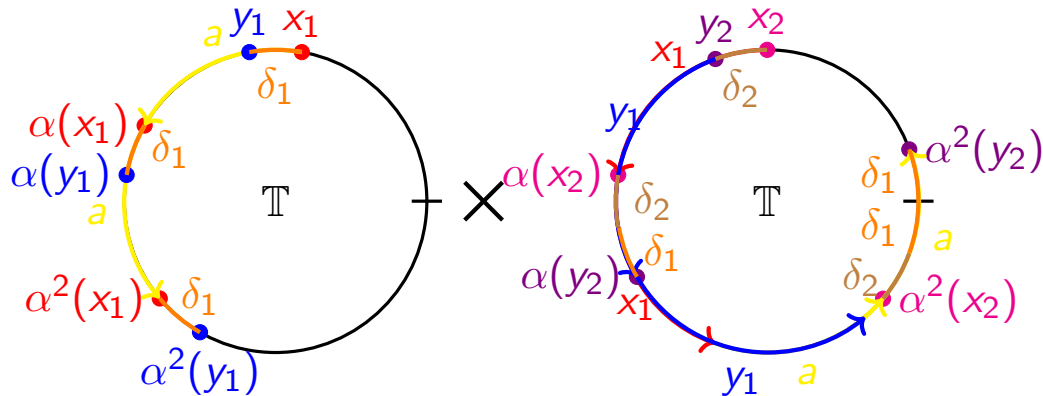
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Fix  $a \in \mathbb{R} \setminus \mathbb{Q}$  and look at  $\mathbb{T}^2 = \mathbb{R}/\mathbb{Z} \times \mathbb{R}/\mathbb{Z}$  with the skew rotation  $\alpha : \mathbb{T}^2 \rightarrow \mathbb{T}^2$  with

$$\alpha([x_1], [x_2]) := ([x_1 + a], [x_2 + x_1]).$$

The arising TDS  $(\mathbb{T}^2, \mathbb{Z})$  is minimal and not equicontinuous.



## Example

The MEF of the skew-rotation  $(\mathbb{T}^2, \alpha)$  is given by the circle rotation  $(\mathbb{T}, r_a)$  with factor map  $\pi$  given by  $([x_1], [x_2]) \mapsto [x_1]$ .

We need to prove that

$$Q_2(\mathbb{T}^2) = R_\pi = \{([x_1], [x_2]), ([y_1], [y_2]) \in \mathbb{T}^2 \times \mathbb{T}^2 \mid [x_1] = [y_1]\}.$$

We already know that  $(\mathbb{T}, r_a)$  is equicontinuous, which implies  $Q_2(\mathbb{T}^2) \subseteq R_\pi$ .

For the other direction we prove that  $(([z], [x]), ([z], [y])) \in R_\pi$  is regional proximal.

Fix  $\varepsilon > 0$ . W.l.o.g.  $0 \leq x \leq y < 1$ . Choose some  $0 < b < \frac{\varepsilon}{2}$  and  $n \in \mathbb{N}_0$  such that

$$0 \leq (y - x) - nb < \frac{\varepsilon}{2}.$$

Then  $([z + b], [x])$  and  $([z], [y])$  are in the  $\varepsilon$  balls around  $([z], [x])$  and  $([z], [y])$  and

$$\begin{aligned} & d_{\mathbb{T}^2}(\alpha^n([z + b], [x]), \alpha^n([z], [y])) \\ &= d_{\mathbb{T}^2}([z + b + na], [x + n(z + b) + \frac{n(n+1)}{n}a], [z + na], [y + nz + \frac{n(n+1)}{2}a]) \\ &\leq b + x - y - nb < \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon \end{aligned}$$

### Remark

Note that for  $([z], [x]) \in \mathbb{T}^2$  and  $n \in \mathbb{N}$  we have

$$\alpha^n([z], [x]) = ([z + na], [x + nz + \frac{n(n-1)}{2}a]).$$

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### Definition ( $m$ -Equicontinuity [GL25; Jin05])

Fix  $m \in \mathbb{N}$ . Then  $(X, T)$  is  $m$ -equicontinuous if for all  $\varepsilon > 0$  there exists a  $\delta > 0$ , such that for all  $U \subseteq X$  open with  $\text{diam}(U) < \delta$ ,  $x_1, \dots, x_m \in U$  and  $t \in T$  there are  $i, j \in \{1, \dots, m\}$  with  $i \neq j$  such that  $d(tx_i, tx_j) < \varepsilon$ .

### Proposition

If  $(X, T)$  is  $m$ -equicontinuous for some  $m \in \mathbb{N}$  it is also  $m'$ -equicontinuous for all  $m' > m$ .

Proof is clear by definition.

Note that the "normal" equicontinuity is 2-equicontinuity.

## Definition ( $m$ -MEF)

Fix  $m \in \mathbb{N}$  with  $m \geq 2$ . Assume that  $(X, T)$  is a minimal TDS and let its MEF be given by  $\pi_{\text{MEF}} : X \rightarrow X_{\text{MEF}}$ . Let  $R_{\pi_{\text{MEF}}}$  be the ICER generated by  $\pi_{\text{MEF}}$ . Let  $\pi : (X, T) \rightarrow (Y, T)$  be a factor and  $R_\pi$  the ICER generated by  $\pi$ . Then  $\pi$  is called a  $m$ -MEF if

$$\forall A \in X/R_{\pi_{\text{MEF}}} \exists B_1, \dots, B_{m-1} \in X/R_\pi : A = \bigcup_{i=1}^{m-1} B_i.$$

Note that the indices of the  $B_i$  only go up to  $m - 1$ ! As before, we have:

## Remark

*Any  $m$ -MEF is also an  $m'$ -MEF for all  $m' > m$  since the  $B_i$  in the definition of an  $m$ -MEF need not be pairwise distinct.*

Importantly, we have

**Proposition (Lemma 4.14 in [GL25])**

*Fix  $m \in \mathbb{N}$  with  $m \geq 2$ . Let  $\pi : (X, T) \rightarrow (Y, T)$  be an  $m$ -MEF. Then  $(Y, T)$  is  $m$ -equicontinuous.*

# Generalizations

We can generalize

- ① the regionally proximal relation to an  $m$ -regionally proximal relation  $Q_m(X) \subset X^m$ .
- ② the diagonal to  
$$\Delta^m(X) := \{(x_1, \dots, x_m) \in X^m \mid \text{there are } i, j \in \{1, \dots, m\} \text{ such that } x_i = x_j\}.$$



And get similarly to before

### Theorem (Theorem 4.6 in [GL25])

*Let  $(X, T)$  be a minimal TDS. Then  $(X, T)$  is  $m$ -equicontinuous if and only if  $Q_m(X) \setminus \Delta^m(X) = \emptyset$  for  $2 \leq m \in \mathbb{N}$ .*

### Theorem ([GL25])

*Let  $(X, T)$  be a minimal TDS and  $\pi : X \rightarrow X_{MEF}$  its MEF. Then  $(X, T)$  is  $m$ -equicontinuous if and only if  $\#\pi^{-1}(\{y\}) < m$  for all  $y \in X_{MEF}$ .*

- 1 Equicontinuity
- 2 Maximal equicontinuous factor
  - Definition,  $\exists!$ , universal property
  - Eigenfunction characterisation and  $C^*$ -algebra approach
  - Relationship to measure preserving system concepts
- 3 The regionally proximal relation
- 4 Example: Skew-Rotation
- 5  $m$ -Equicontinuity
- 6 Thue Morse Subshift

Let  $\sigma$  be the left shift on  $\{0, 1\}^{\mathbb{Z}}$ . Then  $(\{0, 1\}^{\mathbb{Z}}, \sigma)$  is a TDS.

### Example (Thue Morse Subshift)

Take the substitution

$$\begin{cases} 0 \mapsto 01 \\ 1 \mapsto 10 \end{cases}.$$

It has a fixed point  $v \in \{0, 1\}^{\mathbb{Z}}$  and gives a minimal subshift

$$X := \overline{\{\sigma^n v \mid n \in \mathbb{Z}\}}.$$

### Example (Period Doubling Subshift)

Take the substitution

$$\begin{cases} 0 \mapsto 01 \\ 1 \mapsto 00 \end{cases}.$$

It has a fixed point  $w \in \{0, 1\}^{\mathbb{Z}}$  and gives a minimal subshift

$$Y := \overline{\{\sigma^n w \mid n \in \mathbb{Z}\}}.$$

Then there is a 2-to-1 factor  $\pi : X \rightarrow Y$  defined by

$$\pi((a_n)_{n \in \mathbb{Z}}) := \begin{cases} 0 & ; a_n \neq a_{n+1} \\ 1 & ; a_n = a_{n+1} \end{cases}.$$

# Dyadic Odometer

The dyadic integers are given by

$$\begin{aligned}\mathbb{Z}_2 &:= \varprojlim_{k \rightarrow \infty} \mathbb{Z}/2^k\mathbb{Z} \\ &\cong \{(a_k)_{k \in \mathbb{N}} \in \prod_{k \in \mathbb{N}} \{0, \dots, 2^k - 1\} \mid a_{k+1} \in \{a_k, a_k + 2^k\}\}.\end{aligned}$$

Equipped with pointwise addition they form a compact abelian group.

Define  $\eta := (1, 1, \dots) \in \mathbb{Z}_2$  and define  $d : \mathbb{Z}_2 \rightarrow \mathbb{Z}_2$  by  $d(a) := a + \eta$ . Then  $(\mathbb{Z}_2, d)$  is a minimal equicontinuous TDS called the **dyadic odometer**.

There is a factor map  $\rho : Y \rightarrow \mathbb{Z}_2$ , which is at most 2-to-1. In particular  $\mathbb{Z}_2$  is the MEF of  $(Y, T)$  and  $(X, T)$ .

Putting this together we have

Thue Morse subshift:	$(X, \sigma)$	5-equicontinuous
$\pi :$	$\downarrow$	
period doubling subshift:	$(Y, \sigma)$	3-equicontinuous
$\rho :$	$\downarrow$	
dyadic odometer:	$(\mathbb{Z}_2, d)$	(2-)equicontinuous.

In particular  $(\mathbb{Z}_2, d)$  is the MEF of  $(X, \sigma)$  and  $(Y, \sigma)$ . Also  $(Y, \sigma)$  is a 3-MEF of  $(X, \sigma)$ .

Note that however the MEF of  $(\{0, 1\}^{\mathbb{Z}}, \sigma)$  is trivial.

Thanks for your attention!

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